## AN8473SA

## Spindle motor driver IC for optical disk

## ■ Overview

The AN8473SA is an optical disk driver IC, featuring direct PWM drive, DMOS power drive, low ON resistance of output power MOS and $120^{\circ}$ of duty-factor.

## Features

- $\mathrm{R}_{\mathrm{ON}}=0.5 \Omega$ (for both upper and lower)
- 5 V single power source
- Circuit current 7 mA (including step-up circuit current)


## Applications

- Optical disk


Note) The package of this product will be changed to lead-free type (SSOP032-P-0300B). See the new package dimensions section later of this datasheet.

Block Diagram


## - Pin Descriptions

| Pin No. | Symbol | Description | Pin No. | Symbol | Description |
| :---: | :---: | :--- | :---: | :--- | :--- |
| 1 | VH | Hall bias pin | 17 | VM21 | Motor supply voltage pin 2 |
| 2 | H3L | Hall element-3 negative input pin | 18 | VM22 | Motor supply voltage pin 2 |
| 3 | H3H | Hall element-3 positive input pin | 19 | CS | Current det. pin |
| 4 | H2L | Hall element-2 negative input pin | 20 | N.C. | N.C. |
| 5 | H2H | Hall element-2 positive input pin | 21 | A31 | Drive output 3 |
| 6 | H1L | Hall element-1 negative input pin | 22 | A32 | Drive output 3 |
| 7 | H1H | Hall element-1 positive input pin | 23 | PG2 | Power current det. pin 2 |
| 8 | EC | Torque command input pin | 24 | A21 | Drive output 2 |
| 9 | ECR | Torque command reference input pin | 25 | A22 | Drive output 2 |
| 10 | FG | FG signal output pin | 26 | PG1 | Power current det. pin 1 |
| 11 | Start | Start/stop changeover pin | 27 | A11 | Drive output 1 |
| 12 | VPUMP | Booster pin | 28 | A12 | Drive output 1 |
| 13 | BC1 | Booster capacitor connection pin 1 | 29 | N.C. | N.C. |
| 14 | BC2 | Booster capacitor connection pin 2 | 30 | PWMSW | PWM frequency changeover pin |
| 15 | GND | Ground pin | 31 | VM12 | Motor supply voltage pin 1 |
| 16 | VDD | Supply voltage pin | 32 | VM11 | Motor supply voltage pin 1 |

## Absolute Maximum Ratings

| Parameter | Symbol | Rating | Unit |
| :--- | :---: | :---: | :---: |
| Supply voltage ${ }^{* 2}$ | $\mathrm{~V}_{\mathrm{DD}}$ | 6.5 | V |
|  | $\mathrm{~V}_{\mathrm{M} 11,12}$ |  |  |
|  | $\mathrm{~V}_{\mathrm{M} 21,22}$ |  | V |
| Drive output voltage ${ }^{* 5}$ | $\mathrm{~V}_{(\mathrm{m})}$ | 15 | V |
| Control signal input voltage ${ }^{* 6}$ | $\mathrm{~V}_{(\mathrm{n})}$ | 0 to $\mathrm{V}_{\mathrm{DD}}$ | 30 |
| Supply current | $\mathrm{I}_{\mathrm{DD}}$ | $\pm 1200$ | VA |
| Drive output current ${ }^{* 4}$ | $\mathrm{I}_{(\mathrm{o})}$ | 30 | mA |
| Hall bias current ${ }^{* 7}$ | $\mathrm{I}_{\mathrm{HB}(\mathrm{n})}$ | mA |  |
| Power dissipation ${ }^{* 3}$ | $\mathrm{P}_{\mathrm{D}}$ | 293 | mW |
| Operating ambient temperature ${ }^{* 1}$ | $\mathrm{~T}_{\mathrm{opr}}$ | -30 to +85 | ${ }^{\circ} \mathrm{C}$ |
| Storage temperature ${ }^{* 1}$ | $\mathrm{~T}_{\mathrm{stg}}$ | -55 to +150 | ${ }^{\circ} \mathrm{C}$ |

Note) Do not apply external currents or voltages to any pins not specifically mentioned.
For circuit currents, '+' denotes current flowing into the IC, and '-' denotes current flowing out of the IC.
*1: Except for the operating ambient temperature and storage temperature, all ratings are for $\mathrm{T}_{\mathrm{a}}=25^{\circ} \mathrm{C}$.
*2: The voltage in the step-up voltage circuit exceeds the supply voltage.
For the allowable value of the step-up voltage, refer to "■ Electrical Characteristics".
*3: The power dissipation shown is the value of independent IC without a heat sink at $T_{a}=70^{\circ} \mathrm{C}$. Refer to the $P_{D}-T_{a}$ curves of the " $\square$ Application Notes" for details.

$$
\begin{array}{ll}
* 4: \mathrm{o}=17,18,21,22,23,24,25,26,27,28,31,32 & * 5: \mathrm{m}=21,22,24,25,27,28 \\
* 6: \mathrm{n}=2,3,4,5,6,7,8,9,11,30 & * 7: \mathrm{n}=1
\end{array}
$$

Recommended Operating Range

| Parameter | Symbol | Range | Unit |
| :---: | :---: | :---: | :---: |
| Supply voltage | $\mathrm{V}_{\mathrm{DD}}$ | 4.5 to 5.5 |  |
|  | $\mathrm{~V}_{\mathrm{M} 11,12}$ |  |  |
|  | $\mathrm{~V}_{\mathrm{M} 21,22}$ |  |  |

Electrical Characteristics at $\mathrm{T}_{\mathrm{a}}=25^{\circ} \mathrm{C}$

| Parameter | Symbol | Conditions | Min | Typ | Max | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Overall |  |  |  |  |  |  |
| Circuit current 1 | $\mathrm{I}_{\text {DDI }}$ | $\mathrm{V}_{\mathrm{DD}}=5 \mathrm{~V}$ in power save mode | - | 0 | 0.2 | mA |
| Circuit current 2 | $\mathrm{I}_{\mathrm{DD} 2}$ | $\mathrm{V}_{\mathrm{DD}}=5 \mathrm{~V}$ including step-up circuit | - | 7 | 14 | mA |
| Start/stop |  |  |  |  |  |  |
| Start voltage | $\mathrm{V}_{\text {START }}$ | Voltage with which a circuit operates at $\mathrm{V}_{\mathrm{DD}}=5 \mathrm{~V}$ and $\mathrm{L} \rightarrow \mathrm{H}$ | 2.7 | - | - | V |
| Stop voltage | $\mathrm{V}_{\text {STOP }}$ | Voltage with which a circuit becomes off at $V_{D D}=5 \mathrm{~V}$ and $\mathrm{H} \rightarrow \mathrm{L}$ | - | - | 0.7 | V |
| Hall bias |  |  |  |  |  |  |
| Hall bias voltage | $\mathrm{V}_{\mathrm{HB}}$ | $\mathrm{V}_{\mathrm{DD}}=5 \mathrm{~V}, \mathrm{I}_{\mathrm{HB}}=20 \mathrm{~mA}$ | 0.7 | 1.2 | 1.6 | V |
| Hall amplifier |  |  |  |  |  |  |
| Input bias current | $\mathrm{I}_{\text {BH }}$ | $\mathrm{V}_{\mathrm{DD}}=5 \mathrm{~V}$ | - | 1 | 5 | $\mu \mathrm{A}$ |
| In-phase input voltage range | $\mathrm{V}_{\text {HBR }}$ | $\mathrm{V}_{\mathrm{DD}}=5 \mathrm{~V}$, except for $\mathrm{H} 2 \mathrm{H}, \mathrm{H} 2 \mathrm{~L}$ | 1.5 | - | 4.0 | V |
| Minimum input level | $\mathrm{V}_{\text {INH }}$ | $\mathrm{V}_{\mathrm{DD}}=5 \mathrm{~V}$ | 60 | - | - | $\mathrm{mV}[\mathrm{p}-\mathrm{p}]$ |
| Torque command |  |  |  |  |  |  |
| In-phase input voltage range | EC | $\mathrm{V}_{\mathrm{DD}}=5 \mathrm{~V}$ | 0.5 | - | 3.9 | V |
| Offset voltage | $\mathrm{EC}_{\text {OF }}$ | $\mathrm{V}_{\mathrm{DD}}=5 \mathrm{~V}$ | -100 | 0 | 100 | mV |
| Dead zone | $\mathrm{EC}_{\mathrm{DZ}}$ | $\mathrm{V}_{\mathrm{DD}}=5 \mathrm{~V}$ | 0 | 75 | 150 | mV |
| Input current | $\mathrm{EC}_{\text {IN }}$ | $\mathrm{V}_{\mathrm{DD}}=5 \mathrm{~V}, \mathrm{EC}=\mathrm{ECR}=2.5 \mathrm{~V}$ | -5 | -1 | - | $\mu \mathrm{A}$ |
| Input/output gain | $\mathrm{A}_{\text {CS }}$ | $\mathrm{V}_{\mathrm{DD}}=5 \mathrm{~V}, \mathrm{R}_{\mathrm{CS}}=0.33 \Omega$ | 0.36 | 0.48 | 0.60 | A/V |
| Output |  |  |  |  |  |  |
| High-level output saturation voltage | $\mathrm{V}_{\mathrm{OH}}$ | $\mathrm{V}_{\mathrm{DD}}=5 \mathrm{~V}, \mathrm{I}_{\mathrm{O}}=-500 \mathrm{~mA}$ | - | 0.15 | 0.30 | V |
| Low-level output saturation voltage | $\mathrm{V}_{\text {OL }}$ | $\mathrm{V}_{\mathrm{DD}}=5 \mathrm{~V}, \mathrm{I}_{\mathrm{O}}=500 \mathrm{~mA}$ | - | 0.15 | 0.30 | V |
| Torque limit current | $\mathrm{I}_{\text {TL }}$ | $\mathrm{V}_{\mathrm{DD}}=5 \mathrm{~V}, \mathrm{R}_{\mathrm{CS}}=0.33 \Omega$ | 455 | 570 | 685 | mA |
| FG |  |  |  |  |  |  |
| FG output high-level | $\mathrm{FG}_{\mathrm{H}}$ | $\mathrm{V}_{\mathrm{DD}}=5 \mathrm{~V}, \mathrm{I}_{\mathrm{FG}}=-0.01 \mathrm{~mA}$ | 3 | - | - | V |
| FG output low-level | $\mathrm{FG}_{\mathrm{L}}$ | $\mathrm{V}_{\mathrm{DD}}=5 \mathrm{~V}, \mathrm{I}_{\mathrm{FG}}=0.01 \mathrm{~mA}$ | - | - | 0.5 | V |
| In-phase input voltage range | $\mathrm{V}_{\text {FGR }}$ | $\mathrm{V}_{\mathrm{DD}}=5 \mathrm{~V}$ | 1.5 | - | 3.0 | V |
| FG hysteresis width | $\mathrm{H}_{\text {FG }}$ | $\mathrm{V}_{\mathrm{DD}}=5 \mathrm{~V}$ | 5 | 10 | 20 | mV |
| Step-up circuit |  |  |  |  |  |  |
| Step-up voltage | $\mathrm{V}_{\text {PUMP }}$ | $\mathrm{V}_{\mathrm{DD}}=5 \mathrm{~V}$ | 7 | - | 10 | V |

Electrical Characteristics at $\mathrm{T}_{\mathrm{a}}=25^{\circ} \mathrm{C}$ (continued)

| Parameter | Symbol | Conditions | Min | Typ | Max | Unit |
| :--- | :---: | :---: | :---: | :---: | :---: | :---: |
| PWM oscillation changeover |  |  |  |  |  |  |
| Input high-level | $\mathrm{PWM}_{\mathrm{H}}$ | $\mathrm{V}_{\mathrm{DD}}=5 \mathrm{~V}$ | 4.5 | - | - | V |
| Input low-level | $\mathrm{PWM}_{\mathrm{L}}$ | $\mathrm{V}_{\mathrm{DD}}=5 \mathrm{~V}$ | - | - | 0.5 | V |

## - Design reference data

Note) The characteristics listed below are theoretical values based on the IC design and are not guaranteed.

| Parameter | Symbol | Conditions | Min | Typ | Max | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| PWM oscillation changeover |  |  |  |  |  |  |
| PWM frequency high-level | $\mathrm{f}_{\text {PWMH }}$ | $\mathrm{V}_{\mathrm{DD}}=5 \mathrm{~V}, \mathrm{PWMSW}=$ Low | - | 80 | - | kHz |
| PWM frequency low-level | $\mathrm{f}_{\text {PWML }}$ | $\mathrm{V}_{\mathrm{DD}}=5 \mathrm{~V}, \mathrm{PWMSW}=$ High | - | 40 | - | kHz |
| Thermal protection |  |  |  |  |  |  |
| Thermal protection operating temperature | $\mathrm{T}_{\text {SDON }}$ | $\mathrm{V}_{\mathrm{DD}}=5 \mathrm{~V}$ | - | 150 | - | ${ }^{\circ} \mathrm{C}$ |
| Thermal protection hysteresis width | $\Delta \mathrm{T}_{\text {SD }}$ | $\mathrm{V}_{\mathrm{DD}}=5 \mathrm{~V}$ | - | 40 | - | ${ }^{\circ} \mathrm{C}$ |

## Usage Notes

- Prevent this IC from being line-to-ground fault.
(To be concrete, do not short-circuit any of A31 (pin 21), A32 (pin 22), A21 (pin 24), A22 (pin 25), A11 (pin 27) and A12 (pin 28) with GND pin (pin 15).)
- Be careful of the following three pins because their static breakdown voltages are low. ( $\mathrm{C}=200 \mathrm{pF}, \mathrm{R}=0 \Omega$ )

Pin 23: breakdown at 120 V
Pin 26: breakdown at 120 V

## Application Notes

- $\mathrm{P}_{\mathrm{D}}-\mathrm{T}_{\mathrm{a}}$ curves of SSOP032-P-0300



## Application Notes (continued)

- Phase conditions between Hall input and output current

| Phase of Hall pin |  |  |  |
| :---: | :---: | :---: | :---: |
|  | H1H | H2H | H3H |
| A | H | ML | ML |
| B | MH | L | MH |
| C | ML | ML | H |
| D | L | MH | MH |
| E | ML | H | ML |
| F | MH | MH | L |



## Application Circuit Example

(Check the stipulated value of electrical characteristics
and then determine resistance value.)


New Package Dimensions (Unit: mm)

- SSOP032-P-0300B (Lead-free package)

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